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Immersions of surfaces via Spin^c Killing spinors

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Spin Structures: intrinsic point of view

Let (M^n, g) be a compact Riemannian Spin manifold of positive scalar curvature S.

Lichnerowicz (1963):

$$\lambda^2 > \frac{1}{4} \inf_M S.$$

Priedrich (1980):

$$\lambda^2 \ge \frac{n}{4(n-1)} \inf_M \mathcal{S}.$$

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Spin Structures: extrinsic point of view

• Friedrich (1998) proved that

$$(M^2,g) \hookrightarrow \mathbb{R}^3 \iff M^2$$
 carries a generalized Killing spinor.

• Hijazi-Montiel-Zhang (2000): on the compact boundary of a Spin manifold (*Mⁿ*, *g*),

$$\lambda_1 \geqslant \frac{n-1}{2} \inf_M H,$$

where H denotes the mean curvature of the boundary.

Application of the limiting case: an elementary Spin proof of the Alexandrov theorem.

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The shift from Spin to Spin^c

Seiberg-Witten theory (1994)

Donaldson theory (1982)

Applications

- The calculus of the Yamabe invariant (LeBrun-Gursky 1997).
- Topological restrictions on 4-dimensional Einstein manifolds (LeBrun 1995).

Spin^c Structures

- Spin, almost complex, complex, Kähler, Sasaki and some CR manifolds have a canonical ${\rm Spin}^{\rm c}$ structure.
- Hijazi-Montiel-Urbano (2006): let (M^{2m}, g) be a Kähler Einstein manifold of nonnegative scalar curvature.

The restriction of Kählerian ${
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Geometric and topological informations on these submanifolds.

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Definitions

- Let (M^n, g) be an oriented (compact) Riemannian manifold.
 - *M* has a Spin structure $\iff \omega_2(M) = 0$.
 - This condition is very restrictive ($\mathbb{C}P^2$ is not Spin but Spin^c).
 - M has a Spin^c structure ⇐⇒ there exists a complex line bundle L such that

$$\omega_2(M) = [c_1(L)]_{mod 2}.$$

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• The ${\rm Spin}^{\rm c}$ bundle can be written:

$$\Sigma M = \underbrace{\Sigma' M}_{\text{the Spin bundle}} \otimes L^{\frac{1}{2}}.$$

A section $\psi \in \Gamma(\Sigma M)$ is called a spinor field.

 Given a connection on the *auxiliary line bundle L*, we can define a (twisted) connection ∇ on ΣM. The (twisted) Dirac operator is then defined by

$$D: \Gamma(\Sigma M) \longrightarrow \Gamma(\Sigma M)$$
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3-dimensional homogeneous manifolds with 4-dimensional isometry group

- The manifolds 𝔼(κ, τ) are Riemannian fibration over a simply connected 2-dimensional manifold 𝓜²(κ) of curvature κ.
- These manifolds define the geometry of Thurston:

$$\underbrace{\mathbb{S}^2 \times \mathbb{R}}_{\tau=0,\kappa=1}, \underbrace{\mathbb{H}^2 \times \mathbb{R}}_{\tau=0,\kappa=-1}, \underbrace{\mathrm{Nil}_3}_{\tau\neq 0,\kappa=0}, \underbrace{\widetilde{\mathsf{PSL}_2(\mathbb{R})}}_{\tau\neq 0,\kappa<0}.$$

Berger spheres
$$\tau \neq 0, \kappa > 0$$

Restriction to a surface

• The manifolds $\mathbb{E}(\kappa, \tau)$ are Spin^{c} manifolds carrying a Killing spinor ψ of Killing constant $\frac{\tau}{2}$, i.e., a spinor field ψ satisfying, for all vector fields X,

$$\nabla_X \psi = \frac{\tau}{2} X \cdot \psi.$$

• Using the ${\rm Spin}^{\rm c}$ Gauss formula, the restriction of ψ to any oriented surface gives a spinor field ϕ satisfying

$$\nabla_X \varphi = -\frac{1}{2} II(X) \cdot \varphi + i \frac{\tau}{2} X \cdot \overline{\varphi},$$

where $\overline{\varphi} := \varphi_+ - \varphi_-$ is the conjugate of $\varphi = \varphi_+ + \varphi_-$ and II the second fundamental form of the immersion.

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Theorem (with J. Roth, 2011)

The following statements are equivalent:

- (M^2,g) is isometrically immersed into $\mathbb{E}(\kappa,\tau)$ with second fundamental form A and mean curvature H.
- **2** There exists on M a spinor field φ satisfying

$$\begin{cases} \nabla_X \varphi = -\frac{1}{2} A(X) \cdot \varphi + i \frac{\tau}{2} X \cdot \overline{\varphi}, \\ i \Omega(e_1, e_2) = -i(\kappa - 4\tau^2) < \varphi, \frac{\overline{\varphi}}{|\varphi|^2} > \end{cases}$$

③ There exists on M a spinor field arphi satisfying

$$\begin{cases} D\varphi = H\varphi - i\tau\overline{\varphi}, \\ |\varphi| = constant, \\ i\Omega(e_1, e_2) = -i(\kappa - 4\tau^2) < \varphi, \frac{\overline{\varphi}}{|\varphi|^2} > . \end{cases}$$

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A Lawson type correspondence

Theorem (with J. Roth, 2011)

There exists an isometric correspondence between simply connected oriented surfaces minimal in Nil₃ and simply connected oriented surfaces immersed into $\mathbb{H}^2 \times \mathbb{R}$ of mean curvature $\frac{1}{2}$.

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