

Tame geometry: A tribute to  
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and  
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*Effective methods for computing  
the topological invariants  
of real algebraic sets*

# 1 Preliminaries

$F = (f_1, \dots, f_n) : \mathbb{R}^n \rightarrow \mathbb{R}^n$  - a  $C^\infty$ -mapping.

$$\mathcal{J} = \frac{\partial(f_1, \dots, f_n)}{\partial(x_1, \dots, x_n)}$$

(the determinant of the Jacobian matrix)

$B \subset \mathbb{R}^n$  - an open bounded set such that  $\partial B \cap F^{-1}(0) = \emptyset$ .

For almost all  $y \in \mathbb{R}^n$  sufficiently close to  $0 \in \mathbb{R}^n$ :

$$P = \{x \in B \mid F(x) = y\}$$

is finite and

$$\forall p \in P \quad \mathcal{J}(p) \neq 0$$

**Definition.** *The topological degree of  $F$  with respect to  $B$  and  $0 \in \mathbb{R}^n$ :*

$$\deg(F, B, 0) = \sum_{p \in P} \text{sign } \mathcal{J}(p)$$

Let  $\mathbb{R}$  (resp.  $\mathbb{C}$ ) denote the field of real (resp. complex) numbers. Let  $V$  be a finite dimensional real vector space and let

$$\Phi : V \times V \rightarrow \mathbb{R}$$

be a bilinear symmetric form. Let  $V_+$  (resp.  $V_-$ ) denote a maximal subspace of  $V$  on which  $\Phi$  is positive (resp. negative) definite, i.e. if  $x \in V_+ - \{0\}$  (resp.  $x \in V_- - \{0\}$ ) then  $\Phi(x, x) > 0$  (resp.  $\Phi(x, x) < 0$ ). We define

$$\text{signature } \Phi = \dim V_+ - \dim V_-.$$

We shall say that  $\Phi$  is *non-degenerate* if its matrix is non-singular.

**Lemma 1.1** *Let  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  be an  $\mathbb{R}$ -linear functional and let  $\Phi : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  be the bilinear form given by  $\Phi(x, y) = \varphi(xy)$ . Then  $\text{signature } \Phi = \text{sign } \varphi(1)$ . Moreover  $\Phi$  is non-degenerate if and only if  $\varphi(1) \neq 0$ .*

*Proof.* Since  $\varphi$  is  $\mathbb{R}$ -linear then for every  $x \in \mathbb{R} - \{0\}$  we have  $\Phi(x, x) = \varphi(x^2) = \varphi(x^2 \cdot 1) = x^2 \varphi(1)$ . Because  $x^2 > 0$  then

$$\text{signature } \Phi = \text{sign } \varphi(1).$$

**Lemma 1.2** *Let  $\varphi : \mathbb{C} \rightarrow \mathbb{R}$  be an  $\mathbb{R}$ -linear functional and let  $\Phi : \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{R}$  be the bilinear form given by  $\Phi(z, w) = \varphi(zw)$ . Then signature  $\Phi = 0$ .*

*Proof.* Let  $V_+ \subset \mathbb{C}$  denote a maximal  $\mathbb{R}$ -subspace on which  $\Phi$  is positive definite, i.e.  $\Phi(z, z) = \varphi(z^2) > 0$  for every  $z \in V_+ - \{0\}$ . Then  $\sqrt{-1} V_+$  is an  $\mathbb{R}$ -subspace of  $\mathbb{C}$  and if

$$w = \sqrt{-1} z \in \sqrt{-1} V_+ - \{0\}$$

then

$$\Phi(w, w) = \varphi(w^2) = \varphi(-z^2) = -\varphi(z^2) < 0.$$

Hence  $\dim V_- \geq \dim \sqrt{-1} V_+ = \dim V_+$ .

By similar arguments  $\dim V_+ \geq \dim V_-$ . Hence  $\dim V_+ = \dim V_-$  and

$$\text{signature } \Phi = 0. \quad \square$$

Let

$$\mathcal{B} = \mathbb{R} \oplus \cdots \oplus \mathbb{R} \oplus \mathbb{C} \oplus \cdots \oplus \mathbb{C} = \bigoplus_1^m \mathbb{R} \bigoplus_1^r \mathbb{C}.$$

Then  $\mathcal{B}$  is a finite dimensional  $\mathbb{R}$ -algebra. Let  $\varphi : \mathcal{B} \rightarrow \mathbb{R}$  be an  $\mathbb{R}$ -linear functional. Denote

$$\begin{aligned} s_1 &= \varphi(1 \oplus 0 \oplus \cdots \oplus 0), \\ &\quad \vdots \\ s_m &= \varphi(0 \oplus \cdots \oplus 1 \oplus \cdots \oplus 0). \end{aligned}$$

From previous lemmas we get

**Proposition 1.3** *Let  $\Phi : \mathcal{B} \times \mathcal{B} \rightarrow \mathbb{R}$  be the bilinear form given by  $\Phi(f, g) = \varphi(fg)$ . Then*

$$\text{signature } \Phi = \#\{1 \leq i \leq m : s_i > 0\} - \#\{1 \leq i \leq m : s_i < 0\}.$$

*Moreover if  $\Phi$  is non-degenerate then  $s_1 \neq 0, \dots, s_m \neq 0$ .*

Let  $f_1, \dots, f_n \in \mathbb{R}[x_1, \dots, x_n]$ , let  $F_R = (f_1, \dots, f_n) : \mathbb{R}^n \rightarrow \mathbb{R}^n$  and let  $F_C : \mathbb{C}^n \rightarrow \mathbb{C}^n$  be its complexification. Let

$$\mathcal{J} = \frac{\partial(f_1, \dots, f_n)}{\partial(x_1, \dots, x_n)}$$

denote the determinant of the Jacobian matrix. Let  $\mathcal{A} = \mathbb{R}[x_1, \dots, x_n] / I$ , where  $I$  is the ideal in  $\mathbb{R}[x_1, \dots, x_n]$  generated by polynomials  $f_1, \dots, f_n$ . Then  $\mathcal{A}$  is an  $\mathbb{R}$ -algebra.

**From now on we shall assume that  $d = \dim \mathcal{A} < \infty$  and that  $F_C$  has only non-degenerate complex roots, i.e. if  $z \in F_C^{-1}(0)$  then  $\mathcal{J}(z) \neq 0$ .**

The next two facts generalize the Fundamental Theorem of Algebra. They follow immediately from Corollary 1 in [W.Fulton, *Algebraic Curves*], p.57.

**Proposition 1.4**  $\#\{z \in \mathbb{C}^n : F_C(z) = 0\} = \dim \mathcal{A} = d$

So there are  $d$  complex roots for  $F_C$  and we may assume that

$$F_C^{-1}(0) = \{p_1, \dots, p_m, q_1, \bar{q}_1, \dots, q_r, \bar{q}_r\},$$

where  $p_1, \dots, p_m \in \mathbb{R}^n$ ,  $q_1, \dots, q_r \in \mathbb{C}^n - \mathbb{R}^n$  and  $\bar{q}_i$  is the complex conjugate of  $q_i$ . Clearly  $m + 2r = d$ .

If  $f \in I$  then  $f = 0$  on  $F_C^{-1}(0)$ . Then there is an  $\mathbb{R}$ -homomorphism of algebras

$$\Psi : \mathcal{A} \rightarrow \mathcal{B} = \bigoplus_1^m \mathbb{R} \bigoplus_1^r \mathbb{C}$$

given by  $\Psi(f) = f(p_1) \oplus \dots \oplus f(p_m) \oplus f(q_1) \oplus \dots \oplus f(q_r)$ . It is easy to see that  $\dim \mathcal{B} = m + 2r = d = \dim \mathcal{A}$ .

**Theorem 1.5** *If  $f = 0$  on  $F_C^{-1}(0)$  then  $f \in I$ . Hence  $\Psi : \mathcal{A} \rightarrow \mathcal{B}$  is an isomorphism of  $\mathbb{R}$ -algebras. Thus  $g = h$  in  $\mathcal{A}$  if and only if  $g(p_i) = h(p_i)$  for  $1 \leq i \leq m$  and  $g(q_j) = h(q_j)$  for  $1 \leq j \leq r$ .*

## 2 The construction of bilinear forms

Denote  $x = (x_1, \dots, x_n)$ ,  $y = (y_1, \dots, y_n)$ . Define  $\mathcal{A}^2 = \mathbb{R}[x, y]/I_2$ , where  $I_2$  is the ideal in  $\mathbb{R}[x, y]$  generated by  $f_1(x), \dots, f_n(x)$ ,  $f_1(y), \dots, f_n(y)$ . One may check that  $\mathcal{A}^2$  is isomorphic to  $\mathcal{A} \otimes \mathcal{A}$ .

For  $1 \leq i, j \leq n$  define

$$T_{ij}(x, y) = \frac{f_i(y_1, \dots, y_{j-1}, x_j, \dots, x_n) - f_i(y_1, \dots, y_j, x_{j+1}, \dots, x_n)}{x_j - y_j}$$

It is easy to see that each  $T_{ij}$  extends to a polynomial, thus we may assume that  $T_{ij} \in \mathbb{R}[x, y]$ . Define

$$T(x, y) = \det [T_{ij}(x, y)].$$

It is easy to see that  $\mathcal{J}(x) = T(x, x)$ .

**Definition.** The residue class of  $T(x, y)$  in  $\mathcal{A}^2$  is called the *Bezoutian* of  $f_1, \dots, f_n$ .

**Theorem 2.1** *For any polynomial  $q(x)$  we have*

$$q(x)T(x, y) = q(y)T(x, y) \quad \text{in } \mathcal{A}^2.$$

*Proof.* Note  $B_j$  the  $j$ -th column of  $[T_{ij}(x, y)]$ . Then

$$(x_j - y_j)B_j = \begin{bmatrix} f_1(y_1, \dots, y_{j-1}, x_j, \dots, x_k) - f_1(y_1, \dots, y_j, x_{j+1}, \dots, x_n) \\ \vdots \\ f_n(y_1, \dots, y_{j-1}, x_j, \dots, x_k) - f_n(y_1, \dots, y_j, x_{j+1}, \dots, x_n) \end{bmatrix}$$

We do not change the determinant if we add to this column a linear combination of the form

$$\sum_{k \neq j} (x_k - y_k)B_k.$$

The  $j$ -th column then becomes

$$\sum_{k=1}^n (x_k - y_k)B_k = \begin{bmatrix} f_1(x_1, \dots, x_n) - f_1(y_1, \dots, y_n) \\ \vdots \\ f_n(x_1, \dots, x_n) - f_n(y_1, \dots, y_n) \end{bmatrix}$$

Developing this determinant relatively to the  $j$ -th column we get an element of the ideal  $I_2$ . Hence

$$(x_j - y_j)T(x, y) = 0 \quad \text{in } \mathcal{A}^2,$$

and then  $x_j T(x, y) = y_j T(x, y)$  in  $\mathcal{A}^2$ . Hence

$$x_k x_j T(x, y) = x_k y_j T(x, y) = y_k y_j T(x, y) \quad \text{in } \mathcal{A}^2$$

and by induction

$$x_1^{a_1} \cdots x_n^{a_n} T(x, y) = y_1^{a_1} \cdots y_n^{a_n} T(x, y) \quad \text{in } \mathcal{A}^2.$$

So the theorem is true if  $q(x)$  is a monomial. One gets the general case by linearity.

**Proposition 2.2** *Suppose that  $p, q \in F_C^{-1}(0)$ . If  $p = q$  then  $T(p, q) = T(p, p) = \mathcal{J}(p)$ , if  $p \neq q$  then  $T(p, q) = 0$ .*

*Proof.* We have already proved that  $T(p, p) = \mathcal{J}(p)$ . Suppose that  $p \neq q$ . There is a polynomial  $Q(x) \in \mathbb{C}[x]$  such that  $Q(p) \neq 0$  and  $Q(q) = 0$ . Applying the same arguments as in the proof of the previous theorem one can see that there are  $h_1, \dots, h_n, g_1, \dots, g_n \in \mathbb{C}[x, y]$  such that

$$Q(x)T(x, y) = Q(y)T(x, y) + \sum_{i=1}^n h_i(x, y)f_i(x) + \sum_{j=1}^n g_j(x, y)f_j(y).$$

Since  $f_1(p) = \dots = f_n(p) = f_1(q) = \dots = f_n(q) = 0$  then  $Q(p)T(p, q) = Q(q)T(p, q) = 0$ , and then  $T(p, q) = 0$ .

Suppose that  $e_1(x), \dots, e_d(x)$  form a basis in  $\mathcal{A}$ . Since  $\mathcal{A}^2$  is isomorphic to  $\mathcal{A} \otimes \mathcal{A}$  then  $e_i(x)e_j(y)$  for  $1 \leq i, j \leq d$  form a basis in  $\mathcal{A}^2$ . Hence there are  $t_{ij} \in \mathbb{R}$  such that

$$T(x, y) = \sum_{i,j=1}^d t_{ij}e_i(x)e_j(y) = \sum_{i=1}^d e_i(x)\hat{e}_i(y) \text{ in } \mathcal{A}^2,$$

where  $\hat{e}_i = \sum_{j=1}^d t_{ij}e_j$ .

**Theorem 2.3**  $\hat{e}_1, \dots, \hat{e}_d$  form a basis in  $\mathcal{A}$ .

*Proof.* According to Theorem 1.5,  $\mathcal{A}$  is isomorphic to the product  $\mathcal{B} = \bigoplus_1^m \mathbb{R} \bigoplus_1^r \mathbb{C}$ . Let  $E_1, \dots, E_d$  be the basis given by

$$\begin{aligned} E_1 &= 1 \oplus 0 \oplus \dots \oplus 0, \quad E_2 = 0 \oplus 1 \oplus \dots \oplus 0, \dots, \\ E_{m+1} &= 0 \oplus \dots \oplus 1 \oplus \dots \oplus 0, \quad E_{m+2} = 0 \oplus \dots \oplus \sqrt{-1} \oplus \dots \oplus 0, \dots, \\ E_{d-1} &= 0 \oplus \dots \oplus 0 \oplus 1, \quad E_d = 0 \oplus \dots \oplus 0 \oplus \sqrt{-1}. \end{aligned}$$

Using Proposition 1.2 it is easy to see that elements  $\hat{E}_1, \dots, \hat{E}_d$  constructed as above form a basis. Moreover, since  $e_1, \dots, e_d$  are non-singular combinations of  $E_1, \dots, E_d$  then  $\hat{e}_1, \dots, \hat{e}_d$  are non-singular combinations of  $\hat{E}_1, \dots, \hat{E}_d$ , and then they form a basis.

Then there are  $a_1, \dots, a_d \in \mathbb{R}$  such that  $1 = a_1 \hat{e}_1 + \dots + a_d \hat{e}_d$  in  $\mathcal{A}$ . Hence if  $p \in F_C^{-1}(0)$  then

$$a_1 \hat{e}_1(p) + \dots + a_d \hat{e}_d(p) = 1.$$

**Definition** Let  $\varphi : \mathcal{A} \rightarrow \mathbb{R}$  be the linear functional given by

$$\varphi(f) = a_1 b_1 + \dots + a_d b_d,$$

for  $f = b_1 e_1 + \dots + b_d e_d \in \mathcal{A}$ .

The functional  $\varphi$  is called the *Kronecker symbol*, or the *Global Residue*, associated to  $f_1, \dots, f_n$ .

**Lemma 2.4** *If  $p_i \in F_R^{-1}(0)$  for  $1 \leq i \leq m$  and  $T_i(x) = T(x, p_i) \in \mathcal{A}$  then  $\varphi(T_i) = 1$ .*

*Proof.* Since  $T(x, y) = \sum_{j=1}^d e_j(x)\hat{e}_j(y)$  in  $\mathcal{A}^2$  then there are  $h_k, g_k \in \mathbb{R}[x, y]$  such that

$$T(x, y) = \sum_{j=1}^d e_j(x)\hat{e}_j(y) + \sum_{k=1}^n (h_k(x, y)f_k(x) + g_k(x, y)f_k(y)).$$

Because  $f_1(p_i) = \cdots = f_n(p_i) = 0$  then

$$T_i(x) = \sum_{j=1}^d e_j(x)\hat{e}_j(p_i) + \sum_{k=1}^n h_k(x, p_i)f_k(x),$$

and then  $T_i = \hat{e}_1(p_i)e_1(x) + \cdots + \hat{e}_d(p_i)e_d(x)$  in  $\mathcal{A}$ . So

$$\varphi(T_i) = a_1\hat{e}_1(p_i) + \cdots + a_d\hat{e}_d(p_i) = 1.$$

Take  $p_i \in F_R^{-1}(0)$ . We have assumed that  $\mathcal{J}(p) \neq 0$  for every  $p \in F_C^{-1}(0)$ , so  $\mathcal{J}(p_i) \neq 0$ . Let  $t_i = T_i / \mathcal{J}(p_i) \in \mathcal{A}$ . From Proposition 2.2,  $t_i(p_i) = 1$  and  $t_i(q) = 0$  for every  $q \in F_C^{-1}(0)$ ,  $q \neq p_i$ .

Let  $\Psi : \mathcal{A} \rightarrow \mathcal{B}$  be the isomorphism of algebras defined before. Then  $\Psi(t_i) = 0 \oplus \cdots \oplus 1 \oplus \cdots \oplus 0$ , where 1 is in the  $i$ -th factor.

Let  $\Phi : \mathcal{A} \times \mathcal{A} \rightarrow \mathbb{R}$  be the bilinear form given by  $\Phi(f, g) = \varphi(fg)$ .

**Lemma 2.5** signature  $\Phi = \sum_{i=1}^m \text{sign } \mathcal{J}(p_i)$ .

*Proof.* From Lemma 2.4,

$$\varphi(t_i) = \varphi(T_i / \mathcal{J}(p_i)) = \mathcal{J}(p_i)^{-1} \varphi(T_i) = \mathcal{J}(p_i)^{-1}$$

for  $1 \leq i \leq m$ . Then  $\text{sign } \varphi(t_i) = \text{sign } \mathcal{J}(p_i)$ . Now it is enough to apply Proposition 1.3.

Let  $M : \mathbb{R}^n \rightarrow \mathbb{R}$  be a polynomial, let  $\varphi_M : \mathcal{A} \rightarrow \mathbb{R}$  be the linear functional given by  $\varphi_M(f) = \varphi(Mf)$ , let  $\Phi_M : \mathcal{A} \times \mathcal{A} \rightarrow \mathbb{R}$  be the bilinear form given by  $\Phi_M(f, g) = \varphi_M(fg) = \varphi(Mfg)$ .

**Lemma 2.6** signature  $\Phi_M = \sum_{i=1}^m \text{sign } M(p_i) \mathcal{J}(p_i)$ . If  $\Phi_M$  is non-degenerate then  $M(p_i) \neq 0$  for every  $1 \leq i \leq m$ .

*Proof.* Using the same arguments as in the proof of the previous lemma one can show that  $\varphi_M(t_i) = M(p_i) / \mathcal{J}(p_i)$ . From Proposition 2.3,

$$\text{signature } \Phi_M = \sum_{i=1}^m \text{sign } M(p_i) \mathcal{J}(p_i).$$

Moreover, if  $\Phi_M$  is non-degenerate then  $0 \neq \varphi_M(t_i) = M(p_i) / \mathcal{J}(p_i)$ .

### 3 A formula for the topological degree

Let  $F_R = (f_1, \dots, f_n) : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a polynomial mapping, let  $M : \mathbb{R}^n \rightarrow \mathbb{R}$  be a polynomial and let  $B = \{ x \in \mathbb{R}^n : M(x) > 0 \}$ . If  $B$  is bounded and  $\partial B \cap F_R^{-1}(0) = \emptyset$  then  $\deg(F_R, B, 0)$  will denote the topological degree of  $F_R$  with respect to  $B$  and  $0 \in \mathbb{R}^n$ .

Let  $\mathcal{A} = \mathbb{R}[x_1, \dots, x_n] / I$ , where  $I$  is the ideal in  $\mathbb{R}[x_1, \dots, x_n]$  generated by  $f_1, \dots, f_n$ . If  $\dim \mathcal{A} < \infty$  then one may define bilinear forms  $\Phi$  and

$\Phi_M : \mathcal{A} \times \mathcal{A} \rightarrow \mathbb{R}$  the same way as in Section 2.

**Theorem 3.1 (A formula for the topological degree)** *If  $\Phi_M$  is non-degenerate then  $\partial B \cap F_R^{-1}(0) = \emptyset$ . So if  $B$  is bounded then  $\deg(F_R, B, 0)$  is defined and*

$$\deg(F_R, B, 0) = \frac{1}{2}(\text{signature } \Phi + \text{signature } \Phi_M).$$

We give the proof under the additional assumption that all complex roots are non-degenerate, i.e. if  $p \in F_C^{-1}(0)$  then  $\mathcal{J}(p) \neq 0$ . We want to point out that this assumption is not necessary.

*Proof.* From Lemma 2.6,  $M^{-1}(0) \cap F_R^{-1}(0) = \emptyset$ . Since  $\partial B \subset M^{-1}(0)$  then  $\partial B \cap F_R^{-1}(0) = \emptyset$ . According to Theorem 1.4,  $F_R^{-1}(0)$  is finite. In that case

$$\deg(F_R, B, 0) = \sum_{i \in P} \text{sign } \mathcal{J}(p_i),$$

where  $P = \{1 \leq i \leq m : M(p_i) > 0\}$ . From Lemmas 2.5 and 2.6 it is easy to deduce that

$$\deg(F_R, B, 0) = \frac{1}{2}(\text{signature } \Phi + \text{signature } \Phi_M).$$

Using the same arguments one can prove

**Theorem 3.2** *Let  $D \subset \mathbb{R}^n$  be an open bounded set containing all  $F_R^{-1}(0)$ . Then*

$$\deg(F_R, D, 0) = \text{signature } \Phi.$$

**Example 1.**  $F = (x_1^2 - x_2, x_2) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$I = (x_1^2 - x_2, x_2)$$

$$\mathcal{A} = \mathbb{R}[x_1, x_2]/I \simeq \mathbb{R}[x_1]/(x_1^2), \quad \dim \mathcal{A} = 2$$

$$T_{11} = \frac{(y_1^2 - x_2) - (x_1^2 - x_2)}{y_1 - x_1} = y_1 + x_1$$

$$T_{12} = \frac{(y_1^2 - y_2) - (y_1^2 - x_2)}{y_2 - x_2} = -1$$

$$T_{21} = \frac{x_2 - x_2}{y_1 - x_1} = 0$$

$$T_{22} = \frac{y_2 - x_2}{y_2 - x_2} = 1$$

$$T(x, y) = \det \begin{bmatrix} y_1 + x_1 & -1 \\ 0 & 1 \end{bmatrix} = y_1 + x_1$$

$$e_1(x) = 1, e_2(x) = x_1; \quad e_1(y) = 1, e_2(y) = y_1$$

$$T(x, y) = 1 \cdot y_1 + x_1 \cdot 1 = e_1(x)e_2(y) + e_2(x)e_1(y)$$

$$\hat{e}_1 := e_2, \quad \hat{e}_2 := e_1 = 1$$

$$T(x, y) = e_1(x)\hat{e}_1(y) + e_2(x)\hat{e}_2(y)$$

$$1 = 0 \cdot \hat{e}_1 + 1 \cdot \hat{e}_2 \Rightarrow a_1 = 0, a_2 = 1$$

$$\varphi(b_1 \cdot 1 + b_2 \cdot x_1) = a_1 \cdot b_1 + a_2 \cdot b_2 = b_2$$

$$\Phi(e_1, e_1) = \varphi(1 \cdot 1) = 0$$

$$\Phi(e_1, e_2) = \varphi(1 \cdot x_1) = 1$$

$$\Phi(e_2, e_2) = \varphi(x_1 \cdot x_1) = \varphi(x_1^2) = \varphi(0) = 0$$

$$M_\Phi = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \Rightarrow \text{signature } \Phi = 0$$

Theorem 3.2  $\Rightarrow$   $\deg(F_R, D, 0) = 0$ .

## 4 A formula for the local topological degree

$F = (f_1, \dots, f_n) : (\mathbb{R}^n, 0) \rightarrow (\mathbb{R}^n, 0)$  – a polynomial mapping.

Suppose that 0 is isolated in  $F_R^{-1}(0)$ . Define

$$\deg_0(F) = \deg(F_R, \text{int } B(r), 0),$$

where  $B(r) = \{x \mid \|x\| \leq r\}$  and  $\{0\} = F_R^{-1}(0) \cap B(r)$ .

$$Q_0 := \mathbb{R}[[x_1, \dots, x_n]] / (f_1, \dots, f_n),$$

$\mathcal{J}_0$  – the residue class of  $\mathcal{J}$  in  $Q_0$

**Theorem 4.1 (Eisenbud-Levine, Khimshiashvili) .**

(1)  $\dim_{\mathbb{R}} Q_0 < \infty \Rightarrow 0$  is isolated in  $F_C^{-1}(0)$

(2) Let  $\theta_0 : Q_0 \rightarrow \mathbb{R}$  be a linear functional such that  $\theta_0(\mathcal{J}_0) > 0$ .

Define

$$\Theta_0 : Q_0 \times Q_0 \rightarrow \mathbb{R}, \quad \Theta_0(a, b) = \theta_0(ab)$$

Then  $\Theta_0$  is non-degenerate and

$$\deg_0(F) = \text{signature } \Theta_0$$

*Proof:* (as in [5]) Additional assumptions:

(a)  $f_i = g_i + x_i^{2k}$ ,  $2k > \text{degree}(g_i)$

(b) if  $F_C(p) = 0$  and  $p \neq 0$ , then  $\mathcal{J}(p) \neq 0$

$$\begin{aligned} (a) &\Rightarrow x_i^{2k} \equiv -g_i \text{ in } \mathcal{A} \Rightarrow \dim \mathcal{A} = (2k)^n < \infty \\ &\Rightarrow F_C^{-1}(0) \text{ is finite} \Rightarrow 0 \text{ is isolated in } F_C^{-1}(0) \end{aligned}$$

$$\begin{aligned} \varphi : \mathcal{A} &\rightarrow \mathbb{R} \text{ - the Kronecker symbol} \\ \Phi : \mathcal{A} \times \mathcal{A} &\rightarrow \mathbb{R}, \quad : \Phi(a, b) = \varphi(ab) \end{aligned}$$

$$\mathcal{A} = Q_0 \oplus \underbrace{\mathbb{R} \oplus \dots \oplus \mathbb{R}}_{m-1} \oplus \mathbb{C} \oplus \dots \oplus \mathbb{C}$$

The  $(2k)^n \times (2k)^n$ -matrix of  $\Phi$  (of even dimension) is of the form

$$\begin{bmatrix} 0 & 0 & \dots & 0 & 1 \\ 0 & 0 & \dots & 1 & * \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 1 & \dots & * & * \\ 1 & * & \dots & * & * \end{bmatrix}$$

$$0 = \text{signature } \Phi = \text{signature } \Phi|_{Q_0 \times Q_0} + \sum_2^m \text{sign } \mathcal{J}(p_i)$$

Let  $D \subset \mathbb{R}^n$  be an open bounded set containing all  $F_R^{-1}(0)$ . By Theorem 3.2,

$$0 = \deg(F_R, D, 0) = \deg(F_R, B(r), 0) + \sum_2^m \text{sign } \mathcal{J}(p_i)$$

$$\text{signature } \Phi|_{Q_0 \times Q_0} = \deg(F_R, B(r), 0) = \deg_0(F)$$

$$\varphi_0 := \varphi|_{Q_0} : Q_0 \rightarrow \mathbb{R}$$

$$\Phi_0 = \Phi|_{Q_0 \times Q_0} : Q_0 \times Q_0 \rightarrow \mathbb{R}$$

**Theorem 4.2** ([5, 6, 27])  $\varphi_0(\mathcal{J}_0) = \dim Q_0 > 0$

**Theorem 4.3** ([4, 5, 6, 20, 27]) *Let  $\lambda : Q_0 \rightarrow \mathbb{R}$ . Then  $\lambda(\mathcal{J}_0) \neq 0$  if and only if  $\Lambda(a, b) = \lambda(ab) : Q_0 \times Q_0 \rightarrow \mathbb{R}$  is non-degenerate.*

$$\varphi_0(\mathcal{J}_0) > 0 \quad , \quad \theta_0(\mathcal{J}_0) > 0$$

$$\lambda_t := t\varphi_0 + (1-t)\theta_0$$

$$\forall t \in [0, 1] \quad \lambda_t(\mathcal{J}_0) > 0$$

$$\forall t \in [0, 1] \quad \Lambda_t(a, b) := \lambda_t(ab) \text{ -- non-degenerate}$$

$$\text{signature } \Phi_0 = \text{signature } \Lambda_1 = \text{signature } \Lambda_0 = \text{signature } \Theta_0$$

$$\text{signature } \Theta_0 = \text{signature } \Phi_0 = \text{signature } \Phi|_{Q_0 \times Q_0} = \text{deg}_0(F)$$

**Example 2.**  $F(x_1, x_2) = (x_1^2 - x_2^2, 2x_1x_2)$

$$I = (x_1^2 - x_2^2, 2x_1x_2) \subset \mathbb{R}[[x_1, x_2]]$$

$$x_2^3 = -x_2(x_1^2 - x_2^2) + \left(\frac{1}{2}x_1\right) \cdot 2x_1x_2 \in I$$

$$Q_0 = \mathbb{R}[[x_1, x_2]]/I \simeq \mathbb{R}[x_1, x_2]/(x_1^2 - x_2^2, x_1x_2, x_2^3)$$

$$x_1^2 \equiv x_2^2, \quad x_1x_2 \equiv 0, \quad x_2^3 \equiv 0$$

$$Q_0 = \{b_1 \cdot 1 + b_2 \cdot x_1 + b_3 \cdot x_2 + b_4 \cdot x_2^2\}$$

$$\mathcal{J}_0 = \det \begin{bmatrix} 2x_1 & -2x_2 \\ 2x_2 & 2x_1 \end{bmatrix} = 4(x_1^2 + x_2^2) \equiv 8x_2^2$$

$$\theta_0(b_1 \cdot 1 + b_2 \cdot x_1 + b_3 \cdot x_2 + b_4 \cdot x_2^2) = b_4$$

$$\theta_0(\mathcal{J}_0) = 8 > 0$$

$$M_{\Theta_0} = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{signature } \Theta_0 = 2$$

$$\text{deg}_0(F) = 2$$

## 5 Local invariants for functions

$f : (\mathbb{R}^n, 0) \rightarrow (\mathbb{R}, 0)$  - a polynomial

$$S(r) = \{x \mid \|x\| = r\}$$

$$L(r) = S(r) \cap f^{-1}(0)$$

$$A_{\pm}(r) = S(r) \cap \{\pm f \geq 0\}$$

If  $r > 0$  is small enough then the topology of  $L(r)$ ,  $A_+(r)$ ,  $A_-(r)$  is well-defined up to homeomorphism.

**Theorem 5.1 (Sullivan)** *The Euler characteristic  $\chi(L(r))$  is even.*

$$\nabla f = \left( \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right) : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

**Definition.**  $p$  is a *regular* (resp. *critical*) point of  $f$  if  $\nabla f(p) \neq 0$  (resp.  $\nabla f(p) = 0$ ). Put

$$J_f = \det \left[ \frac{\partial^2 f}{\partial x_i \partial x_j} \right] = \mathcal{J}_{\nabla f}$$

A critical point  $p$  is *non-degenerate* if  $J_f(p) \neq 0$

$f$  has an *isolated critical point at the origin* if  $B(r) \cap \nabla f^{-1}(0) = \{0\}$ . If that is the case then  $\deg_0(\nabla f)$  is well defined.

**Theorem 5.2 (Khimshvili)** *If  $f$  has an isolated critical point at the origin then*

$$\chi(A_-(r)) = 1 - \deg_0(\nabla f)$$

$$\chi(A_+(r)) = 1 + (-1)^{n+1} \deg_0(\nabla f)$$

$$\chi(L(r)) = \begin{cases} 0 & \text{if } n \text{ is odd} \\ 2(1 - \deg_0(\nabla f)) & \text{if } n \text{ is even} \end{cases}$$

Fix  $0 < y \ll r \ll 1$ . Put

$$C(f) = B(r) \cap f^{-1}(-y)$$

$$D(f) = B(r) \cap f^{-1}([-y, y])$$

(Łojasiewicz):  $\chi(D(f)) = 1$

(Milnor):  $\chi(A_-(r)) = \chi(C(f))$

Let  $g$  be a function having only non-degenerate critical points which is sufficiently close to  $f$  together with all derivatives of order one and two.

$$\begin{aligned} \chi(D(g)) = \chi(D(f)) &\Rightarrow \chi(D(g)) = 1 \\ \chi(C(g)) = \chi(C(f)) &\Rightarrow \chi(C(g)) = \chi(A_-(r)) \end{aligned}$$

$$\Delta := \{x \in B(r) \mid \nabla g(x) = 0\}$$

$$1 = \chi(D(g)) = (\text{Morse theory}) = \chi(C(g)) + \sum_{p \in \Delta} \text{sign } J_g(p) =$$

$$\chi(C(g)) + \deg(\nabla g, B(r), 0) = (\nabla g \text{ is close to } \nabla f) =$$

$$\chi(A_-(r)) + \deg(\nabla f, B(r), 0) = (\nabla f \text{ has an isolated zero at } 0) =$$

$$\chi(A_-(r)) + \deg_0(\nabla f)$$

## 6 Local invariants for curves

$H = (h_1, \dots, h_{n-1}) : (\mathbb{R}^n, 0) \rightarrow (\mathbb{R}^{n-1}, 0)$  - a polynomial mapping  
 $DH(x)$  - the derivative of  $H$  at  $x$

Suppose that  $\{x \mid H(x) = 0, \text{rank } DH(x) < n - 1\} \cap B(r) \subset \{0\}$ .  
Then near the origin  $H^{-1}(0)$  is a finite union of half-branches emanating from the origin.

$b$  - the number of half-branches equals  $\# H^{-1}(0) \cap S(r)$ .

$$\Omega_H = \det \begin{bmatrix} x_1 & \cdots & x_n \\ \frac{\partial h_1}{\partial x_1} & \cdots & \frac{\partial h_1}{\partial x_n} \\ \vdots & \vdots & \vdots \\ \frac{\partial h_{n-1}}{\partial x_1} & \cdots & \frac{\partial h_{n-1}}{\partial x_n} \end{bmatrix}$$

$$F_H = (\Omega_H, h_1, \dots, h_{n-1}) : (\mathbb{R}^n, 0) \rightarrow (\mathbb{R}^n, 0)$$

**Theorem 6.1 (Aoki, Fukuda, Nishimura, Sun)**  $0$  is isolated in  $F_H^{-1}(0)$ , and

$$b = 2 \cdot \deg_0(F_H)$$

*Proof.* Take  $G = (g_1, \dots, g_{n-1})$  close to  $H$  such that  $G^{-1}(0) \cap B(r)$  is a finite union of smooth curves transversal to  $S(r)$ .

$$b = 2 \cdot \# \text{ arcs in } G^{-1}(0) \cap B(r)$$

$$F_G = (\Omega_G, g_1, \dots, g_{n-1}) : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$x \in F_G^{-1}(0) \Leftrightarrow x \text{ is a critical point of } \|x\|_{|G^{-1}(0)}$$

One may assume that if  $F_G(p) = 0$  then  $\mathcal{J}_{F_G}(p) \neq 0$ .

$\mathcal{J}_{F_G}(p) > 0 \Rightarrow \|x\|_{|G^{-1}(0)}$  has a minimum at  $p$

$\mathcal{J}_{F_G}(p) < 0 \Rightarrow \|x\|_{|G^{-1}(0)}$  has a maximum at  $p$

$$\deg_0(F_H) = \deg(F_H, B(r), 0) = (H \text{ is close to } G) =$$

$$\deg(F_G, B(r), 0) = \sum_{p \in F_G^{-1}(0)} \text{sign } \mathcal{J}_{F_G}(p) =$$

$$\# \text{ min of } \|x\|_{|G^{-1}(0)} - \# \text{ max of } \|x\|_{|G^{-1}(0)} =$$

$$\# \text{ arcs in } G^{-1}(0) \cap B(r)$$

$$b = 2 \cdot \deg_0(F_H)$$

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